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### Variable center of rotation concerning the physiological motion of the knee theorem

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#### Declaration

Given the natural flexion/extension movement of the knee as a combination of rolling and sliding during the first 30° of flexion; subsequently the real flexion depends upon the position of the center of rotation.

This implies that there is a difference between the knee angle measured with a goniometric system and the real distance between the foot and the axis of rotation.

#### Hypothesis

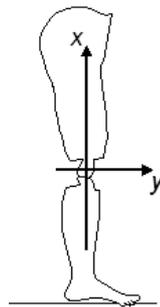
After an initial circular rotating phase, the flexion/extension movement of the knee proceeds with a combination of rolling and sliding (rotary - traslational) motion, which is characterized by the progressive decrease of the distance between the starting rotation and the articular surface.

#### Thesis

The knee flexion/extension axis achieved after a rolling and sliding motion, is different from the axis measured only with a protractor; thus a correct evaluation of the flexion/extension motion of the knee should consider the instantaneous displacement of center of rotation.

#### Proof

The position of the instantaneous center of rotation of the knee is initially placed on the x axis as an extension of the longitudinal axis of the thigh, whereas during the full extension of the thigh, it overlaps the longitudinal axis x of the leg itself. In this case the initial center of rotation of the knee coincides with the origin of Cartesian coordinate system xOy.



Nota 1

Provided that  $R_a$  is the first rotating radius that lies on the y axis, we could describe the gradual displacement of the axis of rotation of the knee, the trajectory of flexion and extension of the leg on the thigh can be analytically defined as:

according to  $\alpha < 30^\circ$ , the knee motion can be described as a rigid system that rotates around a fixed center: the trajectory performed by the point P is the equation of circumference

$$x^2 + y^2 = R_a^2.$$

According to  $30^\circ \leq \alpha < 135^\circ$ , the center of rotation moves toward the articular surface by an amount equal to  $\Delta_x$ .

The new coordinates of point P become:

$$X = x + \Delta_x$$

$$Y = y + \Delta_y$$

The equation of the center of rotation of the knee appears to be:

$$X^2 + Y^2 = R_b^2$$

when  $R_b$  is the real (effective) radius of rotation changing with the mutation of  $\alpha$ , when  $R_b < R_a$

When  $\alpha$  is the angle between the x-axis and the radius of rotation, the values of x, X, y and Y can be obtained as:

$$x = R_a \sin \alpha$$

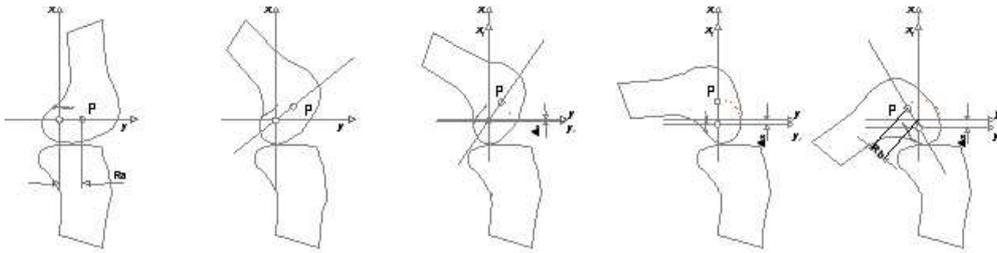
$$y = R_a \cos \alpha$$

$$X = R_b \sin \alpha$$

$$Y = R_b \cos \alpha$$

So when a given value of  $\alpha$  is included between  $30^\circ$  and  $135^\circ$  the position of the instantaneous center of rotation can be calculated as:

$$\Delta_x = X - x = (R_a - R_b) \text{ sen } \alpha$$



### Practical application – The new scale angle

As seen from above, it appears that the rolling and sliding motion the peripheral point P follows a curve with a spiral process, receding toward the center.

This implies that the scale for the evaluation of the actual angle of the knee must be established by the sequence of extreme points P of radius  $R_a$ , which second end (it initially overlaps with the origin of the reference xOy system) after  $30^\circ$  it moves along the x axis within a degree equal to  $\Delta_x$

Therefore the angular reference information on the spiral curve (Fig. 1) must be placed according to the new source xO'Y as a result of the instantaneous shift of the goniometric system along the x axis, when  $O' = O + \Delta_x$ , as a new instantaneous center of rotation.

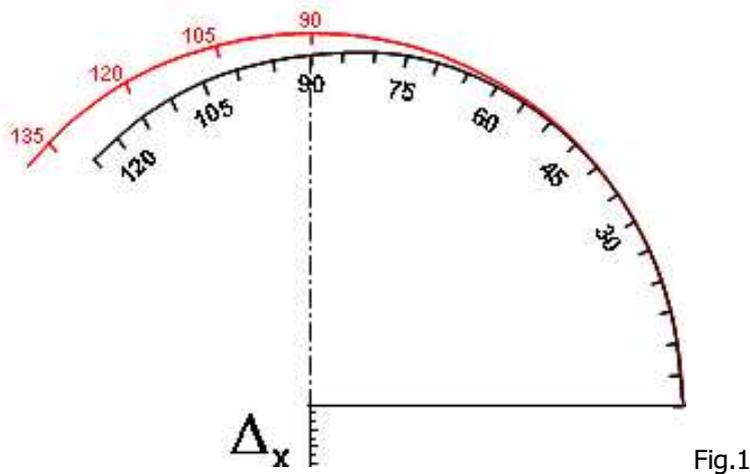


Fig. 1 – Angular scale concerning  $R_a = 13\text{mm}$  and  $\Delta_x = 3,6\text{mm}^1$

### Reference

- 1) Pellis G., Di Cosmo F.: Il moto roto-traslatorio: Studio sperimentale, analisi matematica, dispositivo ortopedico, Calzetti Editore, Perugia, Atti del XVIII edizione del Convegno di Traumatologia e Riabilitazione Sportiva, Bologna, 2009.